

***Resolving Grounding Line  
Dynamics with the BISICLES  
AMR Ice Sheet Model***

**Dan Martin**

**Lawrence Berkeley National Laboratory**

**AGU 2012**

**December 5, 2012**



U.S. DEPARTMENT OF  
**ENERGY**

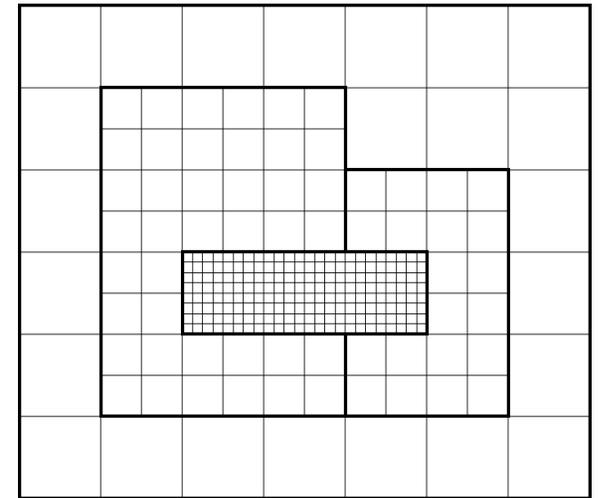
Office of  
Science

**BISICLES**

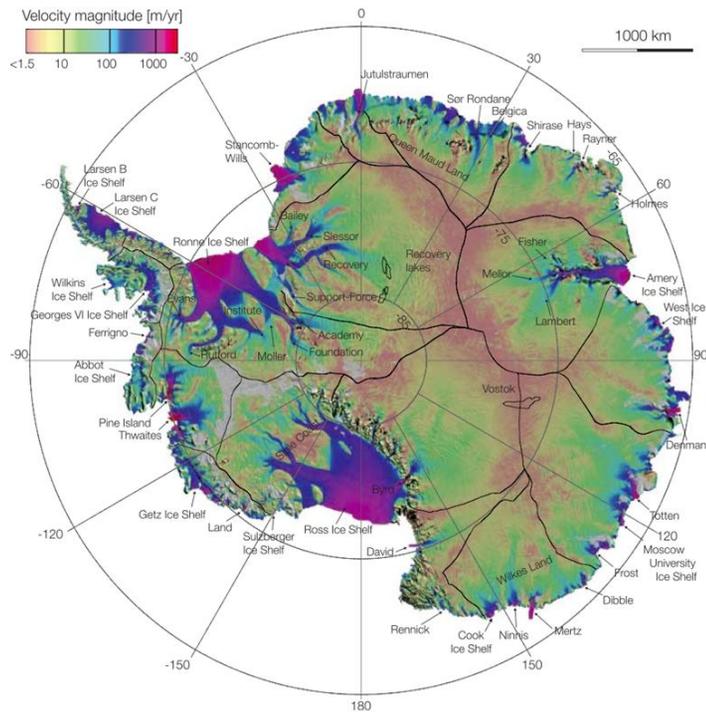


# Berkeley-ISICLES (BISICLES)

- ❑ DOE ISICLES-funded project to develop a scalable adaptive mesh refinement (AMR) ice sheet model/dycore
  - Local refinement of computational mesh to improve accuracy
- ❑ Use Chombo AMR framework to support block-structured AMR
  - Support for AMR discretizations
  - Scalable solvers
  - Developed at LBNL
  - DOE ASCR supported (FASTMath)
- ❑ Interface to CISM (and CESM) as an alternate dycore
- ❑ Collaboration with LANL and Bristol (U.K.)
- ❑ Continuation in SciDAC-funded PISCEES effort



# Why is this useful? (another BISICLE for another fish?)



- Ice sheets -- Localized regions where high resolution needed to accurately resolve ice-sheet dynamics (500 m or better at grounding lines)
- Antarctica is really big - too big to resolve at that level of resolution.
- Large regions where such fine resolution is unnecessary (e.g. East Antarctica)
- Well-suited for adaptive mesh refinement (AMR)
- Problems still large: need good parallel efficiency
- Dominated by nonlinear coupled elliptic system for ice velocity solve: good linear and nonlinear solvers

Rignot et al., *Science*, **333** (2011)



U.S. DEPARTMENT OF  
**ENERGY**

Office of  
Science

**BISICLES**



# “L1L2” Model (Schoof and Hindmarsh, 2010).

- Uses asymptotic structure of full Stokes system to construct a higher-order approximation
  - Expansion in  $\varepsilon = \frac{[H]}{[L]}$  and  $\lambda = \frac{[\tau_{shear}]}{[\tau_{normal}]}$  (ratio of shear & normal stresses)
    - Large  $\lambda$ : shear-dominated flow
    - Small  $\lambda$ : sliding-dominated flow
  - Computing velocity to  $O(\varepsilon^2)$  only requires  $\tau$  to  $O(\varepsilon)$
- Computationally **much** less expensive -- enables fully 2D vertically integrated discretizations. (can reconstruct 3d)
- Similar formal accuracy to Blatter-Pattyn  $O(\varepsilon^2)$ 
  - Recovers proper fast- and slow-sliding limits:
    - SIA ( $1 \ll \lambda \leq \varepsilon^{-1/n}$ ) -- accurate to  $O(\varepsilon^2 \lambda^{n-2})$
    - SSA ( $\varepsilon \leq \lambda \leq 1$ ) - accurate to  $O(\varepsilon^2)$



# “L1L2” Model (Schoof and Hindmarsh, 2010), cont.

□ Can construct a computationally efficient scheme:

1. Approximate constitutive relation relating  $grad(u)$  and stress field  $\tau$  with one relating  $grad(u|_{z=b})$ , vertical shear stresses  $\tau_{xz}$  and  $\tau_{zx}$  given by the SIA / lubrication approximation and other components  $\tau_{xx}(x, y, z)$ ,  $\tau_{xy}(x, y, z)$ , etc
2. leads to an effective viscosity  $\mu(x, y, z)$  which depends only on  $grad(u|_{z=b})$  and  $grad(z_s)$ , ice thickness, etc
3. Momentum equation can then be integrated vertically, giving a nonlinear, 2D, elliptic equation for  $u|_{z=b}(x, y)$
4.  $u(x, y, z)$  can be reconstructed from  $u|_{z=b}(x, y)$



# Temporal Stability

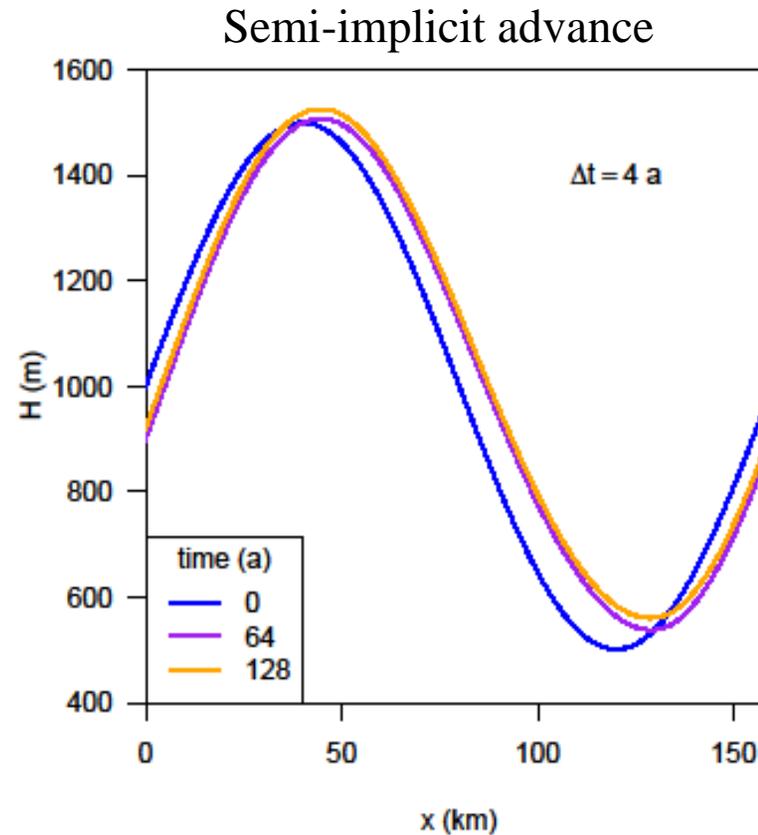
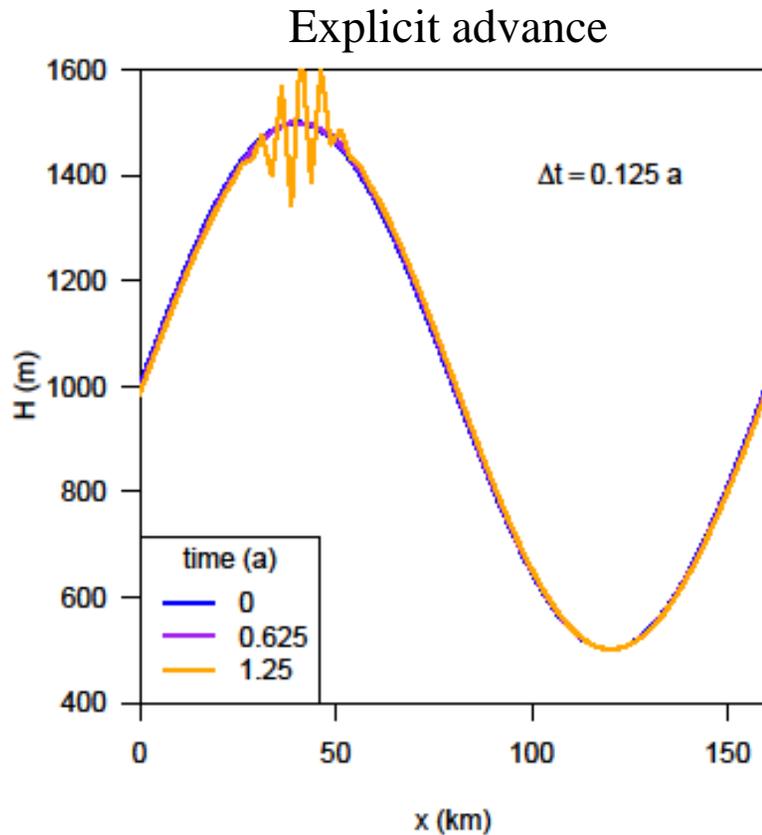
Update equation for H:  $\frac{\partial H}{\partial t} + \nabla \cdot (\vec{u}H) = S$

- ❑ “looks” like hyperbolic advection equation (explicit scheme, Courant stability --  $\Delta t \propto \Delta x$ )
- ❑ Velocity field has  $\nabla H$  piece - diffusion equation for H ( $\Delta t \propto \Delta x^2!$ )
- ❑ Strategy (Cornford) - try to factor out diffusive flux and discretize as an advection-diffusion equation:
  - ❑  $\vec{F} = \vec{u}H = \vec{F}_{advective} + \vec{F}_{diffusive}$
  - ❑  $\vec{F}_{diffusive} = -D \nabla H$
  - ❑ Now solve:  $\frac{\partial H}{\partial t} + \nabla \cdot \vec{F}_{advective} = \nabla \cdot (D \nabla H) + S$ 
    - ❑ Advective fluxes: explicit update using unsplit 2<sup>nd</sup> Order PPM scheme
    - ❑ Diffusive fluxes: implicit update (Backward Euler for now)



# Temporal Stability (cont)

- ❑ Test case based on ISMIP-HOM A geometry
- ❑  $\Delta x = 2.5 \text{ km}, \Delta t_{CFL} = 5 \text{ a}$



- ❑ Unfortunately, still run into stability issues finer than  $\Delta x < 0.5 \text{ km}$ !

# Modified “L1L2” Model (SSA\*)

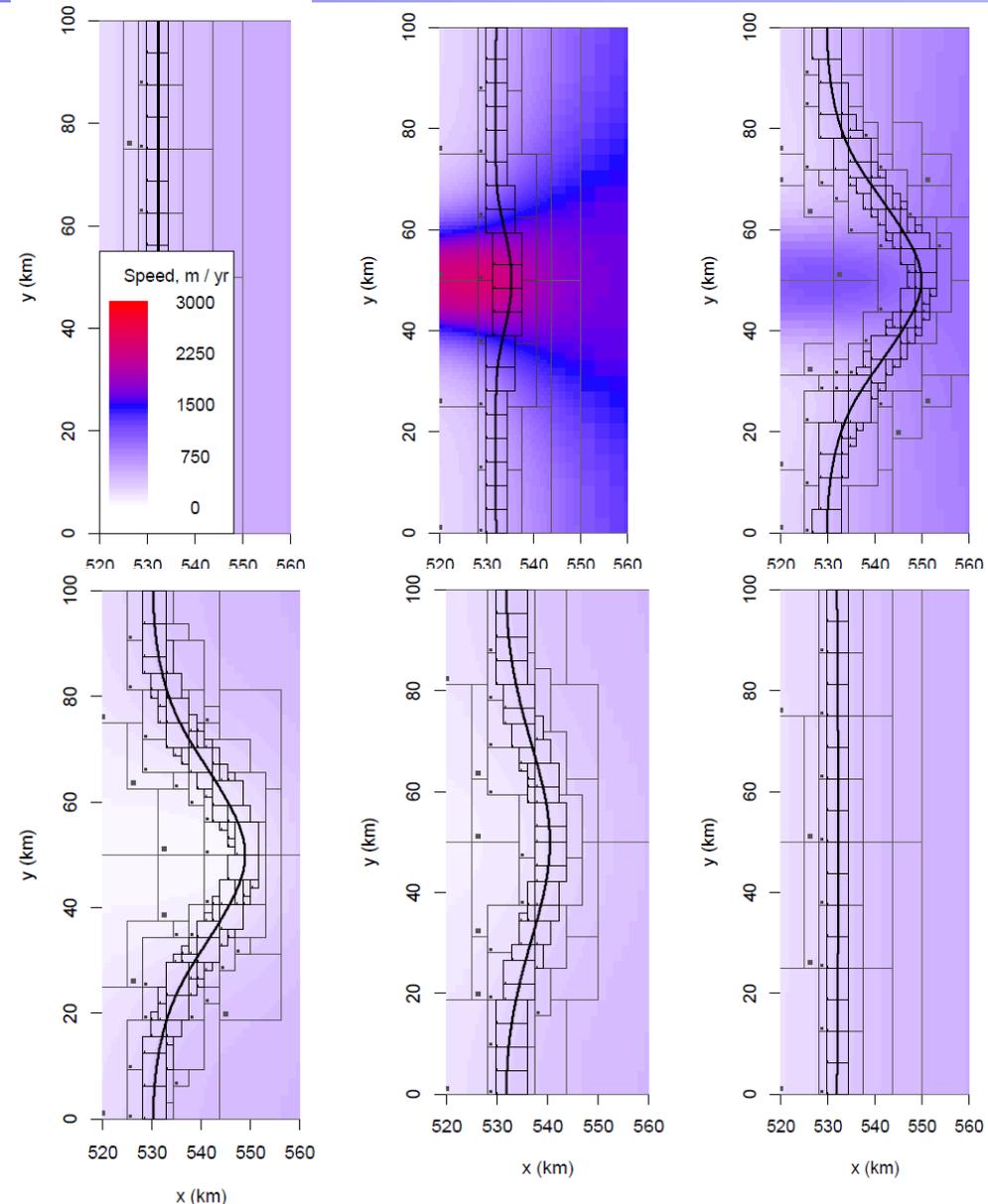
- Use this result to construct a computationally efficient scheme:
  1. Approximate constitutive relation relating  $grad(u)$  and stress field  $\tau$  with one relating  $grad(u|_{z=b})$ , vertical shear stresses  $\tau_{xz}$  and  $\tau_{zx}$  given by the SIA / lubrication approximation and other components  $\tau_{xx}(x, y, z)$ ,  $\tau_{xy}(x, y, z)$ , etc
  2. leads to an effective viscosity  $\mu(x, y, z)$  which depends only on  $grad(u|_{z=b})$  and  $grad(z_s)$ , ice thickness, etc
  3. Momentum equation can then be integrated vertically, giving a nonlinear, 2D, elliptic equation for  $u|_{z=b}(x, y)$
  - ~~4.  $u(x, y, z)$  can be  $u(x, y)$~~
  4. Use  $u(x, y, z) = u|_{z=b}(x, y)$  (neglect vertical shear in flux velocity)



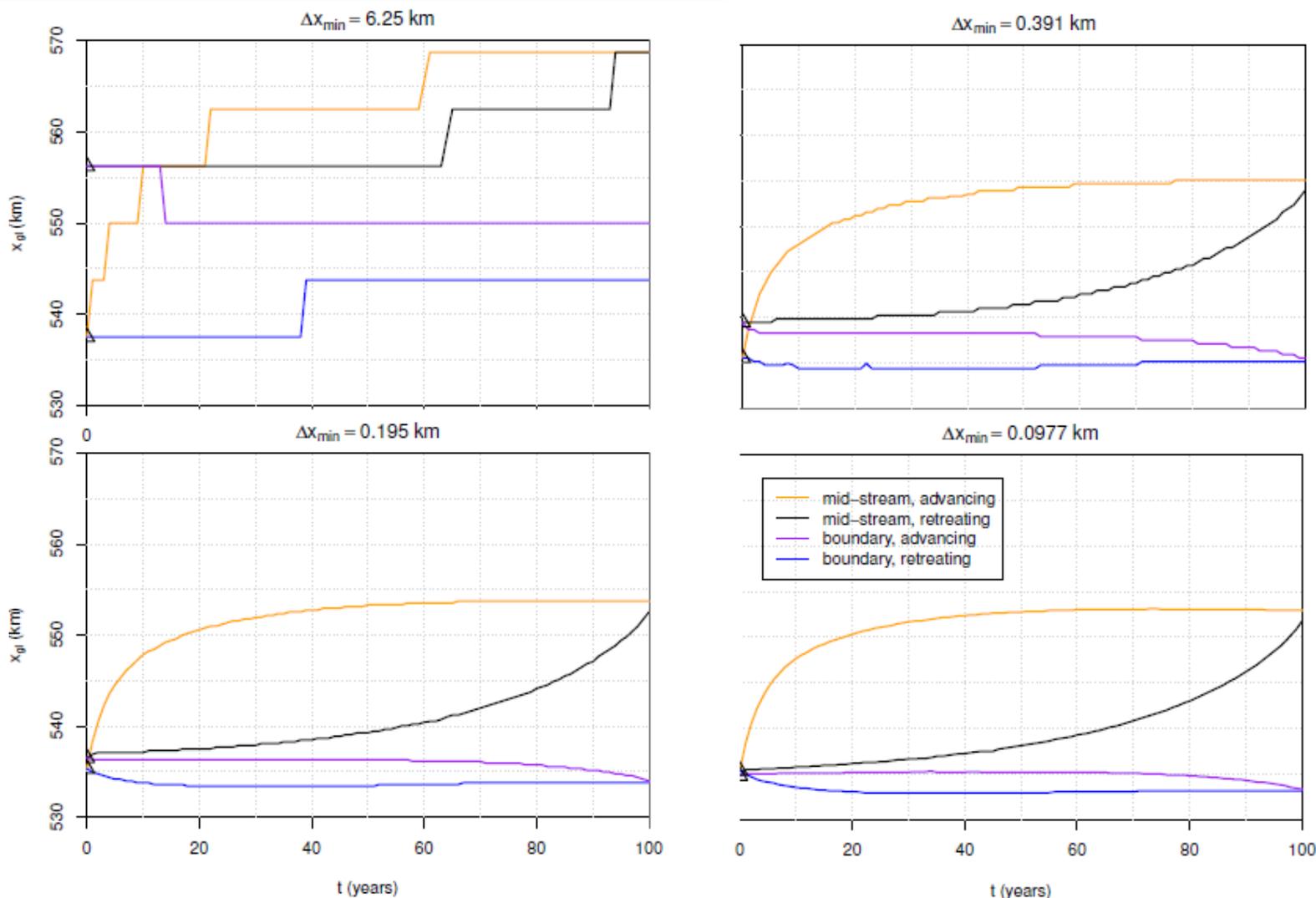
# BISICLES Results - MISMIP3D

## Experiment P75R: (Pattyn et al (2011))

- Begin with steady-state (equilibrium) grounding line.
- Add Gaussian slippery spot perturbation at center of grounding line
- Ice velocity increases, GL advances.
- After 100 years, remove perturbation.
- Grounding line should return to original steady state.
- Figures show AMR calculation:
  - $\Delta x_0 = 6.5km$  base mesh,
  - 5 levels of refinement
  - Finest mesh  $\Delta x_4 = 0.195km$ .
  - $t = 0, 1, 50, 101, 120, 200 yr$
- Boxes show patches of refined mesh.
- GL positions match Elmer (full-Stokes)



# MISMIP3D (cont): L1L2 (SSA\*) Spatial Resolution

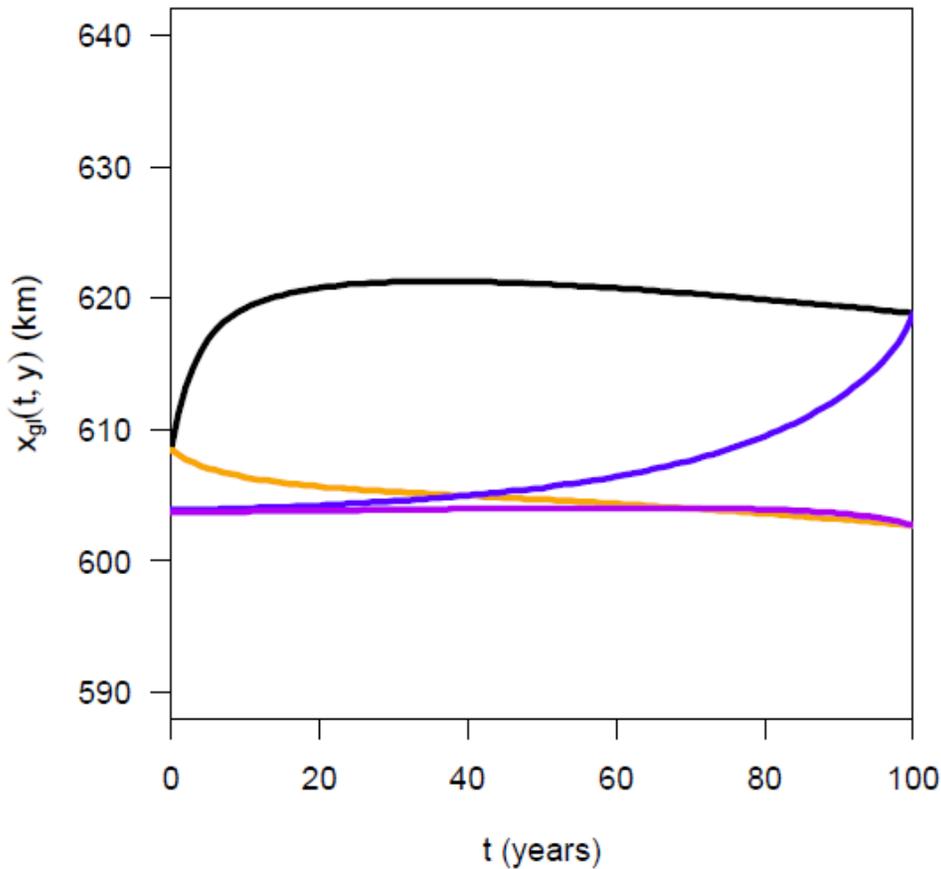


- Very fine (~200 m) resolution needed to achieve reversability!

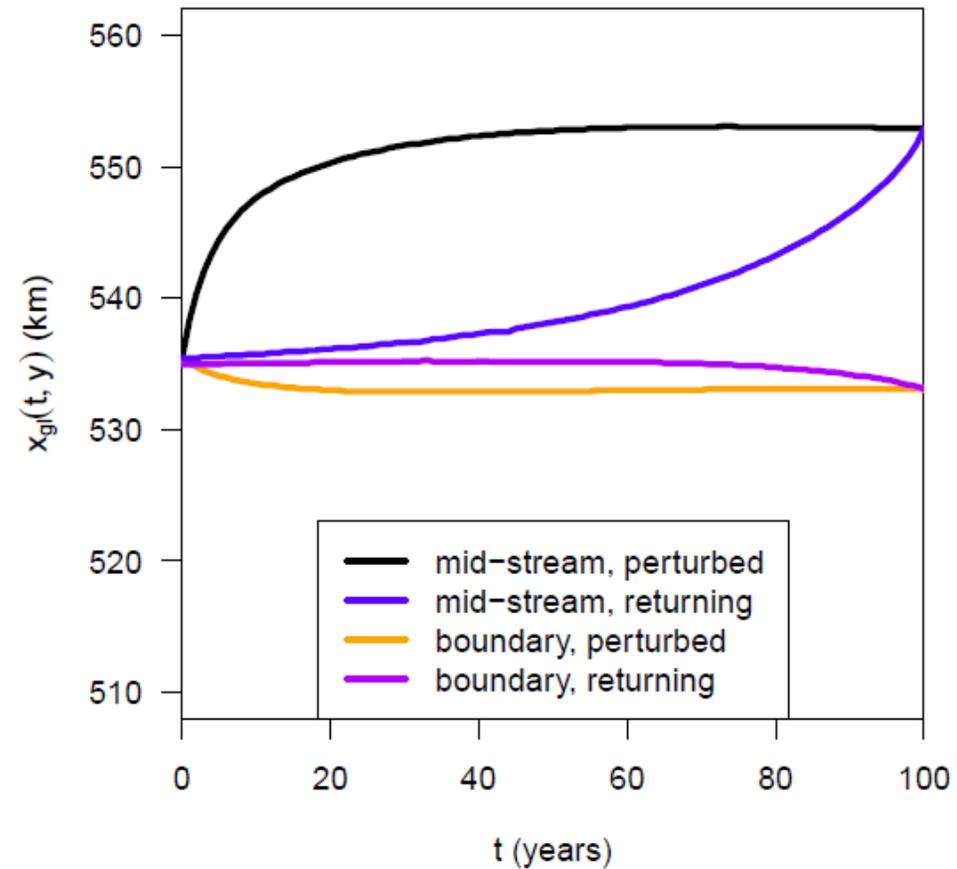


# MISMIP3D: SSA vs. “L1L2” or “SSA\*”

SSA,  $\Delta x^L = 100$  m

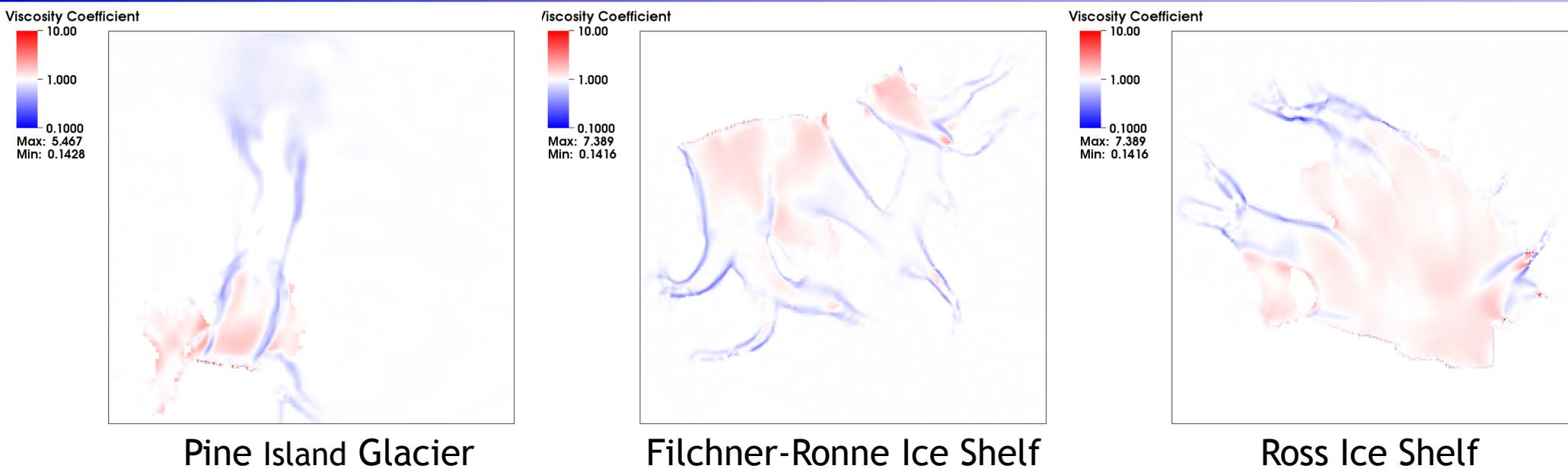


SSA\*,  $\Delta x^L = 100$  m



- Direct comparison of SSA vs. SSA\*
  - (fully resolved spatially, same numerics, etc)
  - Note difference in steady-state GL positions

# Simple Rheology/Damage model



- Solve control problem for ice initial condition
- Include new parameter  $\varphi$  which multiplies viscosity
- $\varphi < 1$  (blue) = softening
- $\varphi > 1$  (red) = hardening

# *BISICLES Results - Ice2Sea Amundsen Sea*

- ❑ Study of effects of warm-water incursion into Amundsen Sea.
- ❑ Results from Payne et al, (2012), submitted.
- ❑ Modified 1996 BEDMAP geometry (Le Brocq 2010), basal traction and damage coefficients to match Joughin 2010 velocity.
- ❑ Background SMB and basal melt rate chosen for initial equilibrium.
- ❑ SMB held fixed.
- ❑ Perturbations in the form of additional subshelf melting:
  - derived from FESOM circumpolar deep water
  - ~5 m/a in 21<sup>st</sup> Century,
  - ~25 m/a in 22<sup>nd</sup> Century.



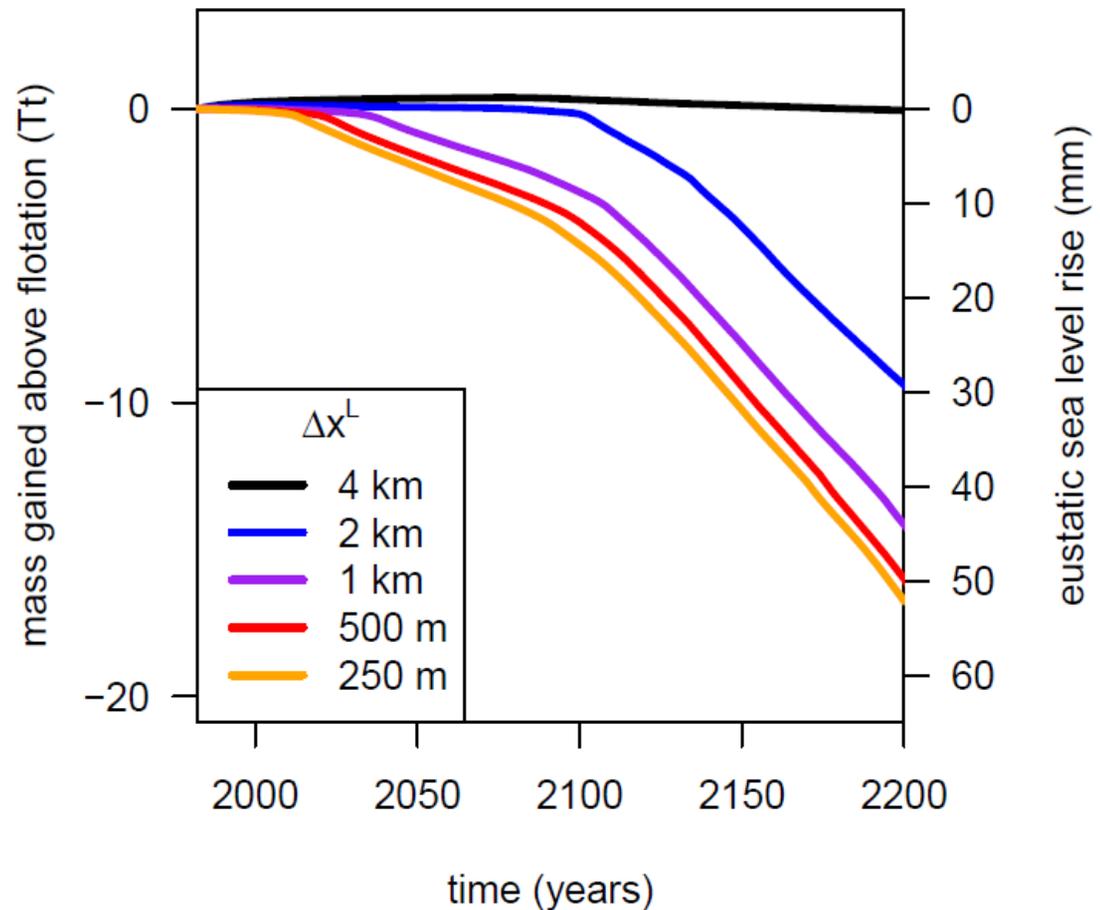
## Amundsen Sea Ice Sheet Simulation

One possible climate scenario (Payne et al.)  
simulated using SciDAC-funded BISICLES code

# Ice2Sea Amundsen (cont)

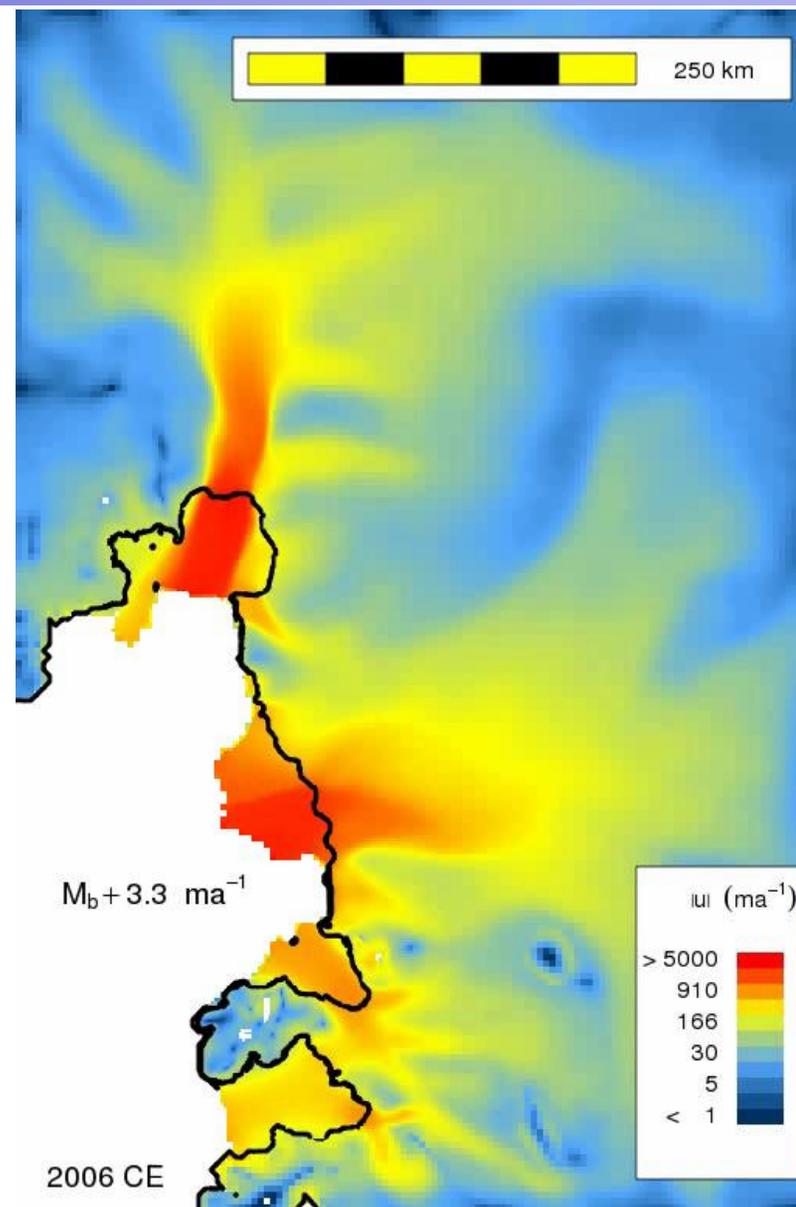
- Need at least 2 km resolution to get any measurable contribution to SLR.
- Appears to converge at first-order in  $\Delta x$

## SLR vs. year, Amundsen Sea Sector



# Ice2Sea Amundsen (cont) - Thwaites?

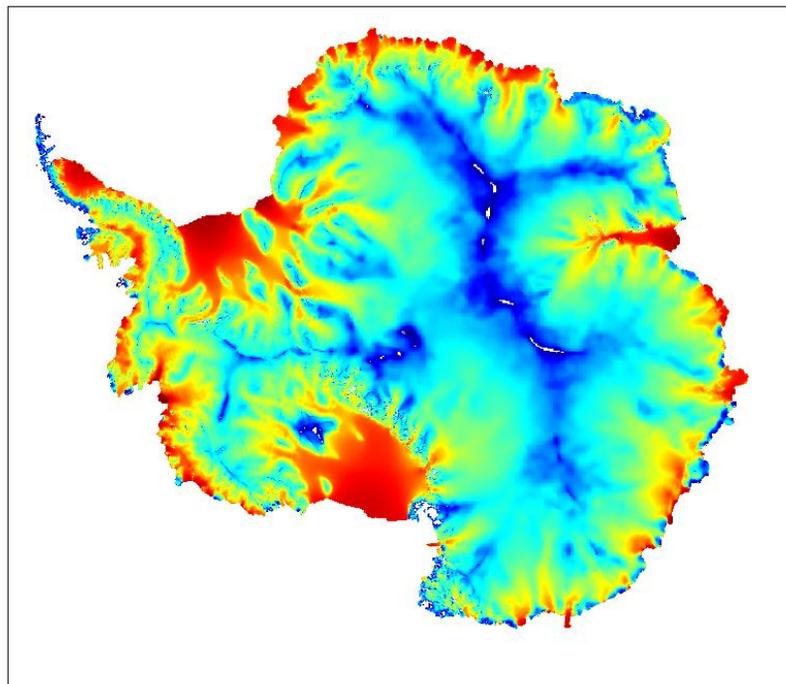
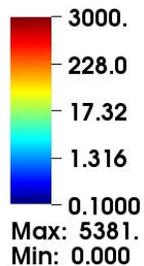
- In 400 year run, Thwaites destabilizes as well.
- Same forcing as previous run, subshelf melting held constant past 2200.
- As discussed by Alley and Parizek (Tuesday morning), Thwaites is very stable, until it tips.



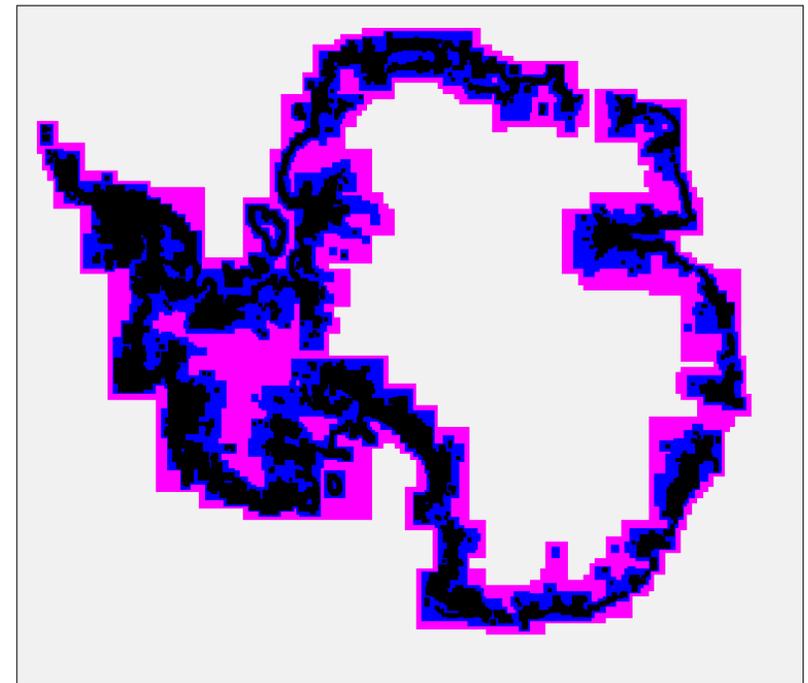
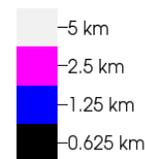
# Antarctica (Ice2Sea)

- Refinement based on Laplacian(velocity), grounding lines
- 5 km base mesh with 3 levels of refinement
  - base level (5 km): 409,600 cells (100% of domain)
  - level 1 (2.5 km): 370,112 cells (22.5% of domain)
  - Level 2 (1.25 km): 955,072 cells (14.6% of domain)
  - Level 3 (625 m): 2,065,536 cells (7.88% of domain)

Mag(Velocity)

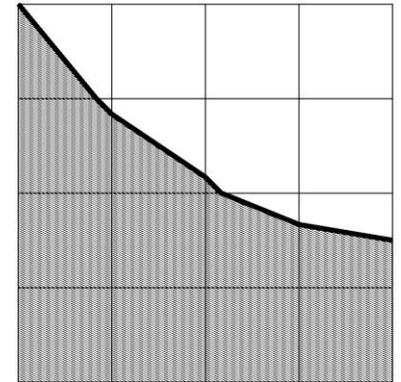
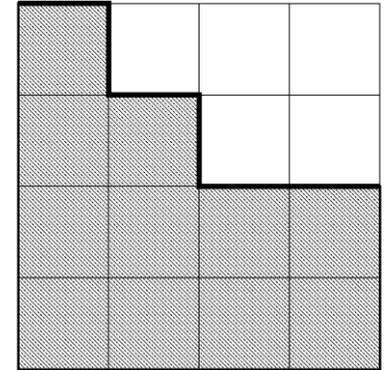


Mesh Resolution



# Embedded Boundary (EB) for Grounding Lines

- **Embedded Boundary (EBChombo)**
  - Currently force GL and ice margins to cell faces
  - “Stair-step” discretization  
Known to be inadequate from experience with Stefan Problem in other contexts!
  - Use Chombo Embedded-boundary support to improve discretization of GL’s and ice margins.
  - Can solve as a Stefan Problem, with appropriate jump conditions enforced at grounding line.  
(as in Schoof, 2007)



# Conclusions

- ❑ Fine (sub 1-km) resolution required to get grounding lines right
- ❑ AMR is a natural fit for this problem
- ❑ Split advective/diffusive approach to temporal evolution looked promising, but was eventually insufficient.
- ❑ “SSA\*” modified L1L2 approach improves temporal stability, appears to be “good enough” for grounding lines and fast-flowing ice streams and shelves.
- ❑ Embedded boundary approach is promising



# Acknowledgements:

- ❑ US Department of Energy Office of Science (ASCR) funded BISICLES project
- ❑ US Department of Energy Office of Science (ASCR/BER) SciDAC applications program (PISCEES)
- ❑ Steph Cornford, Tony Payne at the University of Bristol
- ❑ Bill Lipscomb, Doug Ranken, Stephen Price (LANL)
- ❑ Mark Adams (Columbia University)

# Extras



U.S. DEPARTMENT OF  
**ENERGY**

Office of  
Science

**BISIGLES**





U.S. DEPARTMENT OF  
**ENERGY**

Office of  
Science

**BISIGLES**



# BISICLES - Next steps

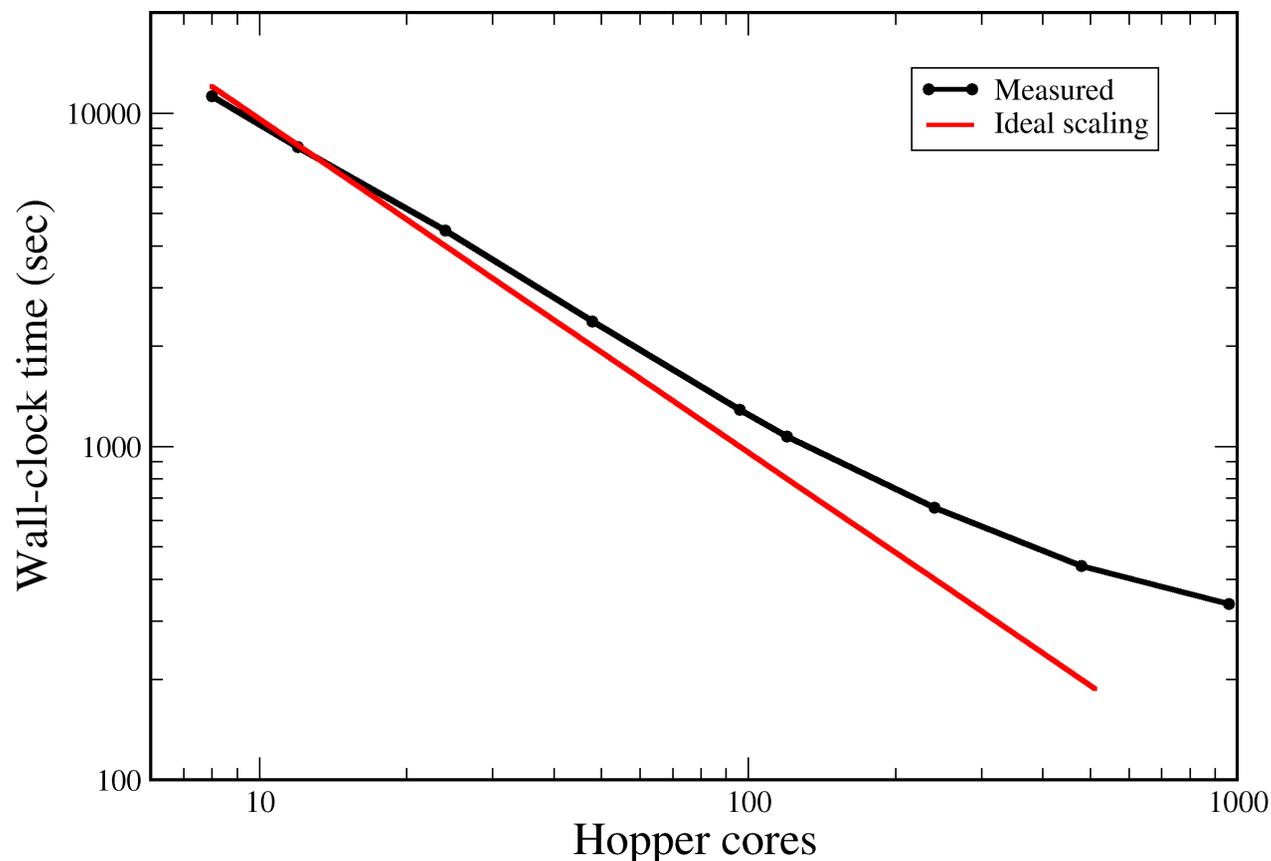
- ❑ More work with linear and nonlinear velocity solves.
  - PETSc/AMG linear solvers look promising (in progress)
- ❑ Revisit semi-implicit time-discretization for stability, accuracy.
- ❑ Finish coupling with existing Glimmer-CISM code and CESM
- ❑ Full-Stokes for grounding lines?
- ❑ Embedded-boundary discretizations for GL's and margins.
- ❑ Performance/scaling optimization and autotuning.
- ❑ Refinement in time?



# Parallel scaling, Antarctica benchmark

Strong Scaling of Antarctica Test Problem

hopper.nersc.gov



(Preliminary scaling result – includes I/O and serialized initialization)



U.S. DEPARTMENT OF  
**ENERGY**

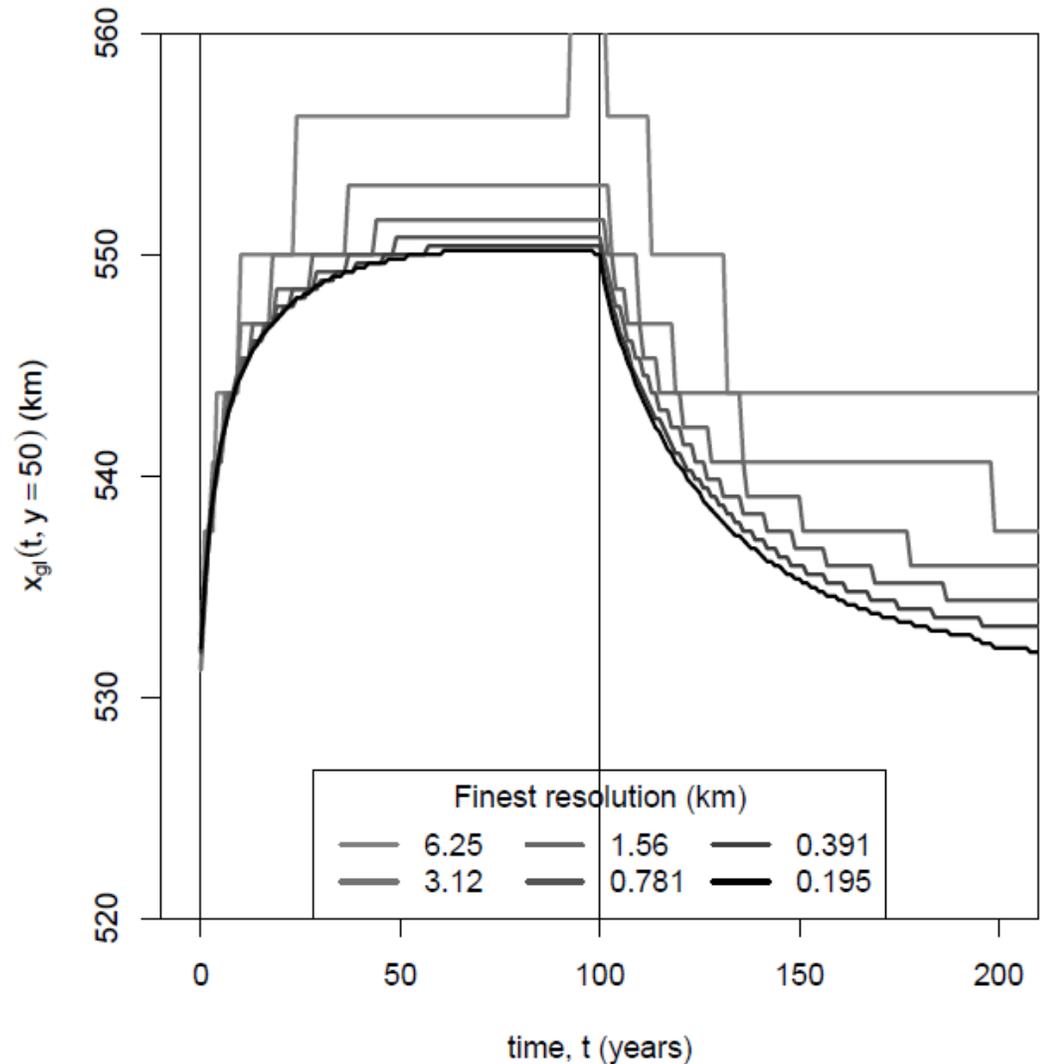
Office of  
Science

**BISIGLES**



# MISMIP3D: Mesh resolution

- Plot shows grounding line position  $x_{GL}$  at  $y = 50\text{km}$  vs. time for different spatial resolutions.
- $\Delta x = 0.195\text{km} \rightarrow 6.25\text{ km}$
- Appears to require finer than 1 km mesh to resolve dynamics
- Converges as  $O(\Delta x)$  (as expected)



# BISICLES: Models and Approximations

**Physics:** Non-Newtonian viscous flow:  $\mu(\dot{\epsilon}^2, T) = A(T)(\dot{\epsilon}^2)^{\frac{(1-n)}{2}}$

## □ Full-Stokes

- Best fidelity to ice sheet dynamics
- Computationally expensive (full 3D coupled nonlinear elliptic equations)

## □ Approximate Stokes

- Use scaling arguments to produce simpler set of equations
- Common expansion is in ratio of vertical to horizontal length scales ( $\epsilon = \frac{[h]}{[l]}$ )
- E.g. Blatter-Pattyn (most common “higher-order” model), accurate to  $O(\epsilon^2)$
- Still 3D, but solve simplified elliptic system (e.g. 2 coupled equations)

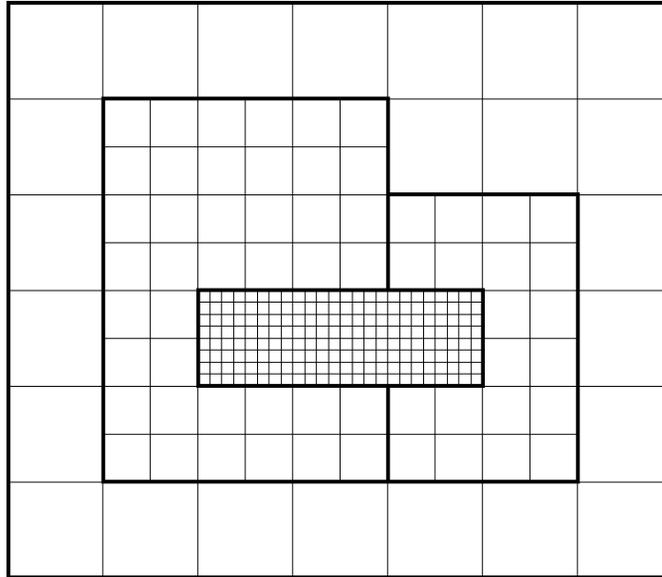
## □ Depth-integrated

- “Shallow Ice” and “Shallow-Shelf” approximations (accurate to  $O(\epsilon)$ )
- Special case of approximate Stokes with 2D equation set
- Easiest to work with computationally, generally less accurate

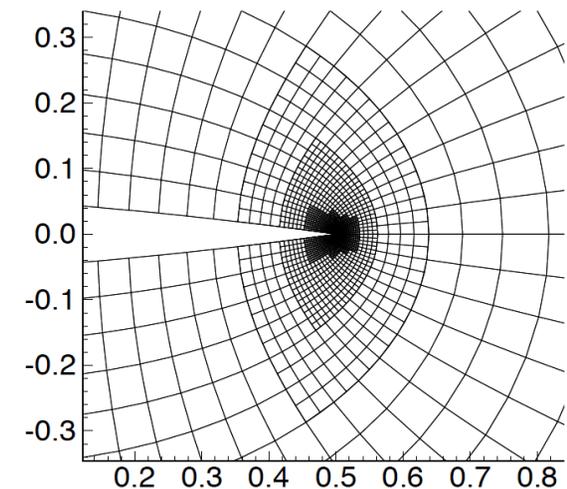
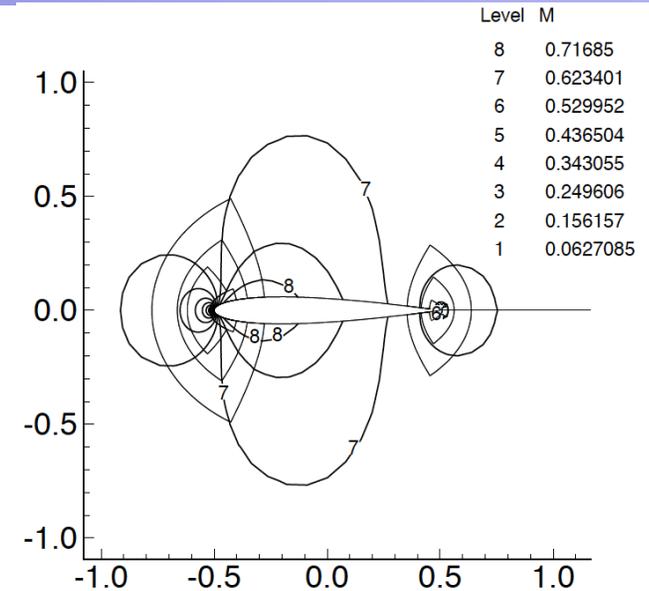


# Block-Structured Local Refinement

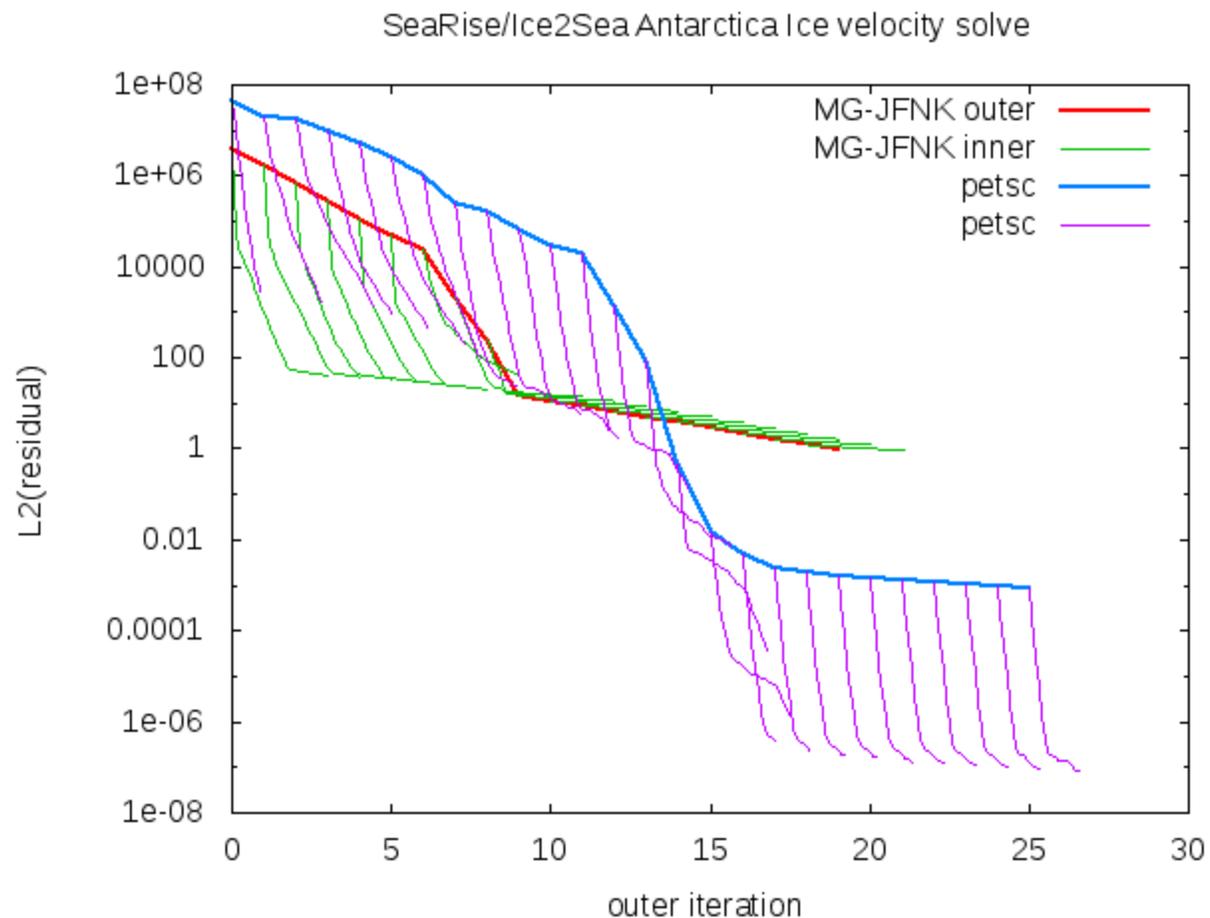
- Refined regions are organized into rectangular patches.



- *Algorithmic advantages:*
  - *Build on mature structured-grid discretization methods.*
  - *Low overhead due to irregular data structures, relative to single structured-grid algorithm.*



# Linear Solvers - GAMG vs. Geometric MG

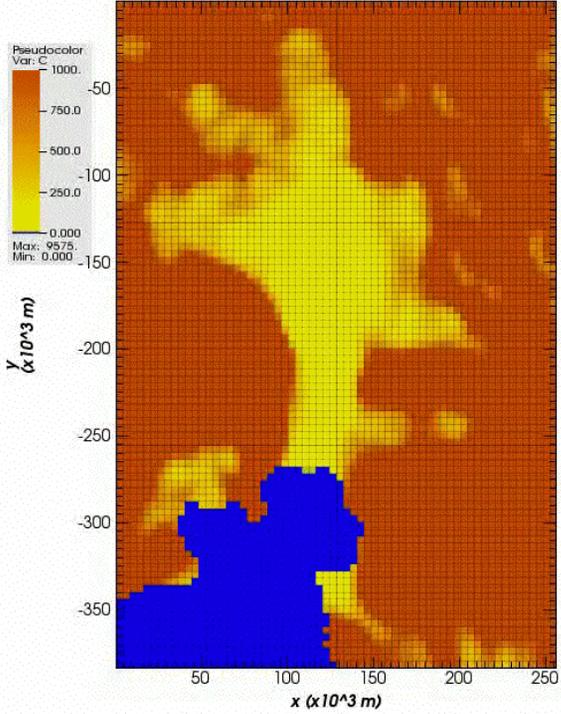


# BISICLES Results - Pine Island Glacier

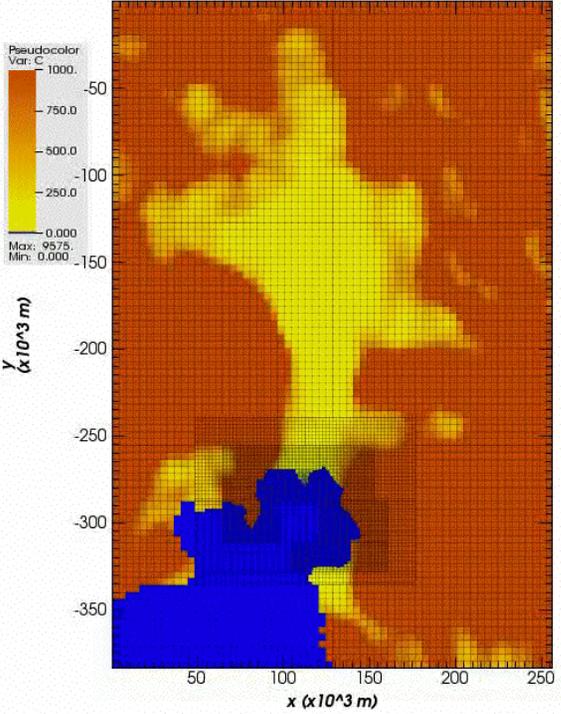
- ❑ Cornford, et al, JCP (2011, submitted)
- ❑ PIG configuration from LeBrocq:
  - Bathymetry: combined Timmerman (2010), Jenkins (2010), Nitsche (2007)
  - AGASEA thickness
  - Isothermal ice,  $A=4.0 \times 10^{-17} \text{ Pa}^{-\frac{1}{3}} \text{ m}^{-1/3} \text{ a}$
  - Basal friction chosen to roughly agree with Joughin (2010) velocities
- ❑ Specify melt rate under shelf:
  - $$M_s = \begin{cases} 0 & H < 50m \\ \frac{1}{9}(H - 50) & 50 \leq H \leq 500m \\ 50 & H > 500m \end{cases} \quad \text{m/a}$$
- ❑ Constant surface flux = 0.3 m/a
- ❑ Evolve problem - refined meshes follow the grounding line.
- ❑ Calving model and marine boundary condition at calving front



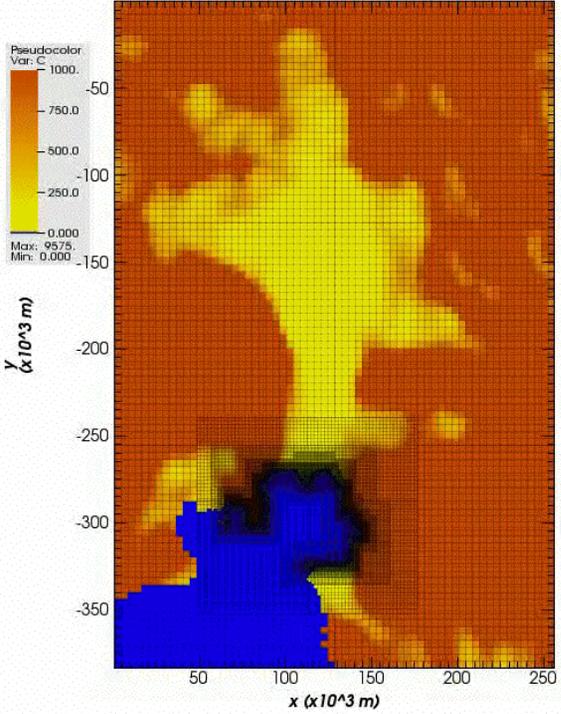
# PIG (cont)



Time=0

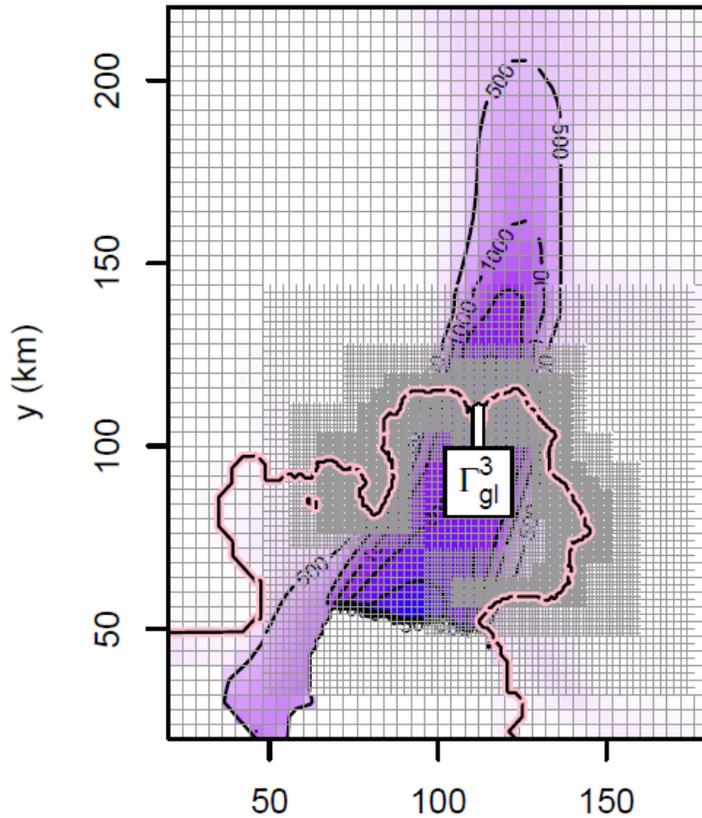


Time=0

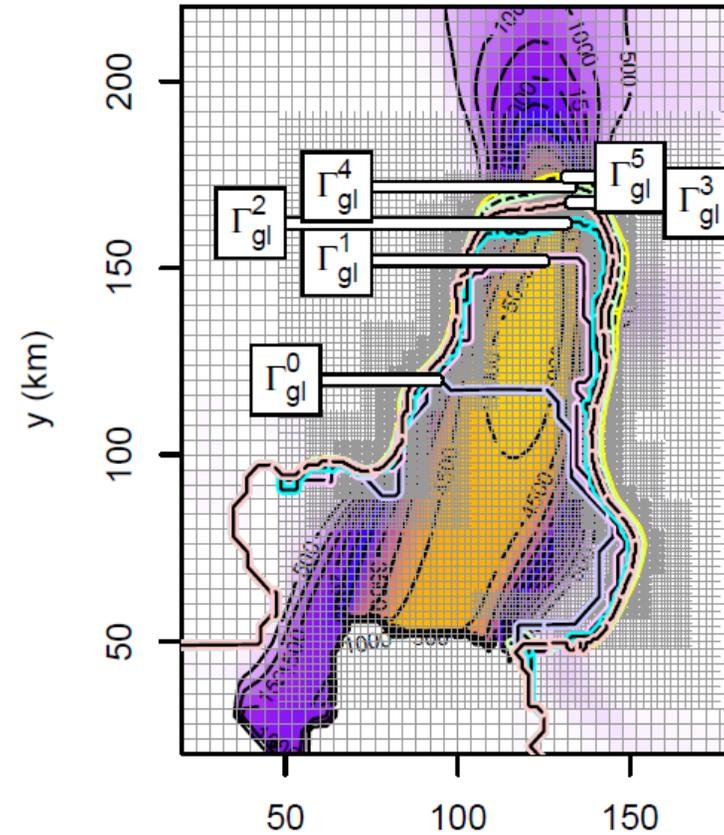


Time=0

# PIG, cont



Initial Condition

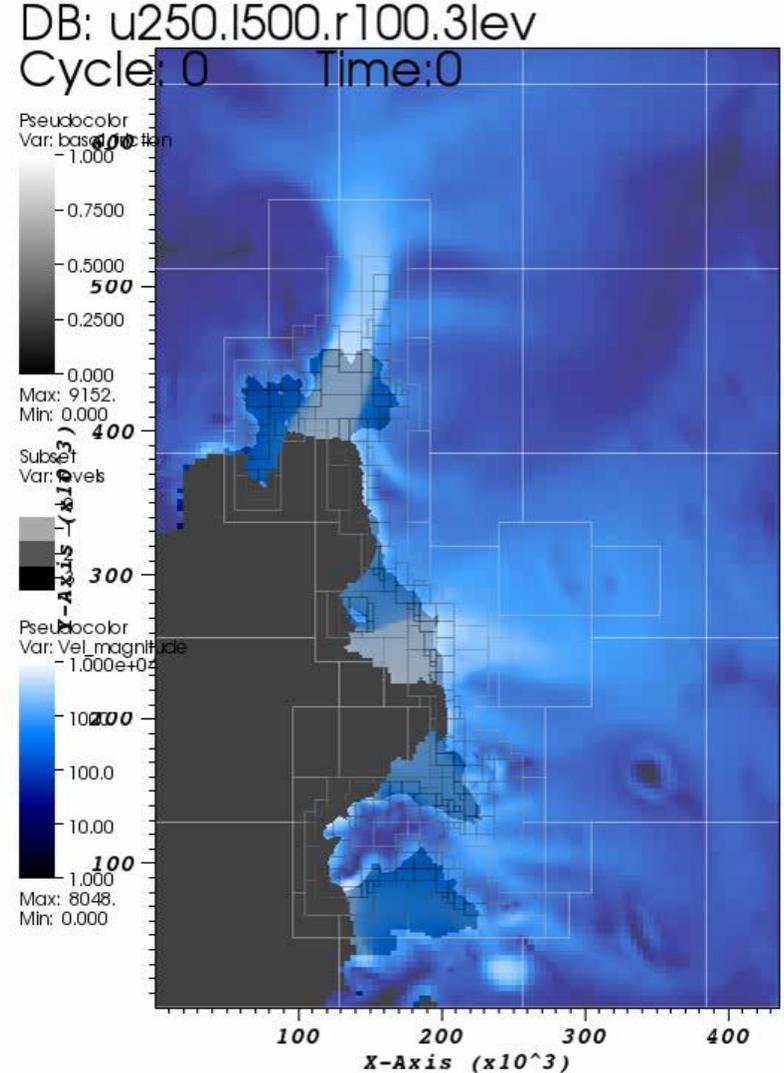


Solution after 30 years

*Coloring is ice velocity,  $\Gamma_{gl}$  is the grounding line. Superscripts denote number of refinements. Note resolution-dependence of  $\Gamma_{gl}$*

# Amundsen Sea Sector

- Regional Model
- Heavy subshelf melting drives retreat (up to 100 m/a)
- Melt rate function of depth (strongest melting near GL)
- 4 km base mesh
- 3 levels of refinement (2km, 1km, 500m)
- Courtesy of Steph Cornford



user: gglic  
Mon Jun 18 14:27:20 2012



U.S. DEPARTMENT OF  
**ENERGY**

Office of  
Science

**BISICLES**



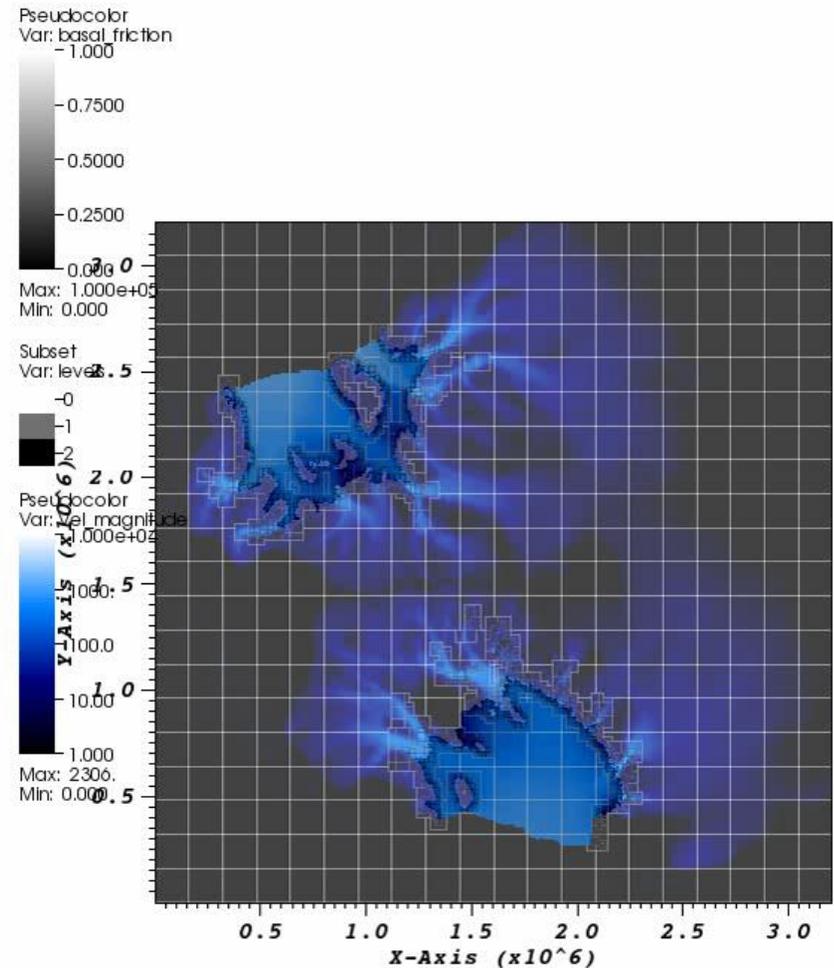
Los Alamos  
NATIONAL LABORATORY  
EST. 1943

University of  
BRISTOL

# Filchner-Ronne/Ross

- Light melting ( $< 5$  m/a)
- 5 km base resolution
- 2 refinement levels (2.5km, 1.25km)
- “few hours” for 32 processors to evolve for 50 yrs
- Courtesy of Steph Cornford
- 

DB: minthck250.maxthck500.rate5.2le  
Cycle: 0 Time:0



user: gglic  
Mon Jun 18 14:49:14 2012



U.S. DEPARTMENT OF  
**ENERGY**

Office of  
Science

**BISICLES**



Los Alamos  
NATIONAL LABORATORY  
EST. 1943

University of  
BRISTOL

# Interface with Glimmer-CISM

- ❑ Glimmer-CISM has coupler to CESM, additional physics
  - Well-documented and widely accepted
- ❑ Our approach - couple to Glimmer-CISM code as an alternate “dynamical core”
  - Allows leveraging existing Glimmer-CISM capabilities
  - Use the same coupler to CESM
  - BISICLES code sets up within Glimmer-CISM and maintains its own storage, etc.
  - Communicates through defined interface layer
  - Instant access to a wide variety of test problems
  - Interface development almost complete
  - Part of larger alternative “dycore” discussion for Glimmer-CISM



# Models and Approximations

## □ Full-Stokes

- Best fidelity to ice sheet dynamics
- Computationally expensive (full 3D coupled nonlinear elliptic equations)

## □ Approximate Stokes

- Use scaling arguments to produce simpler set of equations
- Common expansion is in ratio of vertical to horizontal length scales ( $\varepsilon = \frac{[h]}{[l]}$ )
- E.g. Blatter-Pattyn (most common “higher-order” model), accurate to  $O(\varepsilon^2)$
- Still 3D, but solve simplified elliptic system (e.g. 2 coupled equations)

## □ Depth-integrated

- Special case of approximate Stokes with 2D equation set (“Shelfy-stream”)
- Easiest to work with computationally
- Generally less accurate



# “L1L2” Model (Schoof and Hindmarsh, 2010)

- Asymptotic expansion in 2 flow parameters:
  - $\varepsilon$  -- ratio of length scales  $\frac{[h]}{[x]}$
  - $\lambda$  - ratio of shear to normal stresses  $\frac{[\tau_{shear}]}{[\tau_{normal}]}$ 
    - Large  $\lambda$ : shear-dominated flow
    - Small  $\lambda$ : sliding-dominated flow
- Blatter-Pattyn approximates full-Stokes to  $O(\varepsilon^2)$  for all  $\lambda$  regimes
- Asymptotic expansion: (e.g.  $u(x, z) = u_0 + \varepsilon u_1 + O(\varepsilon^2)$  )
  - Leading order velocity term:  $u_0 = u_0(x)$  (no vertical dependence)
  - Don't need shear stresses to  $O(\varepsilon^2)$  to compute velocity to  $O(\varepsilon^2)$
  - Provides basis for depth-integrated approach



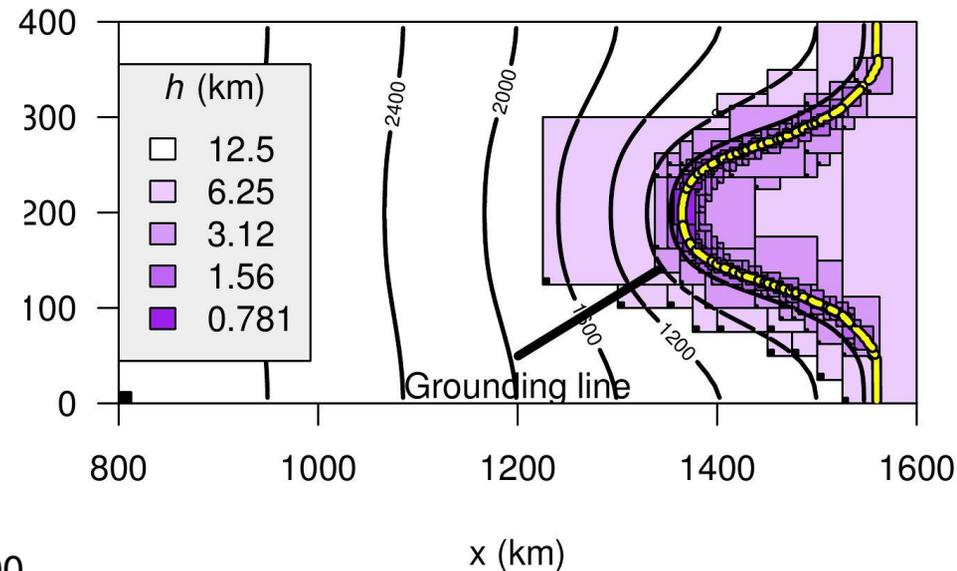
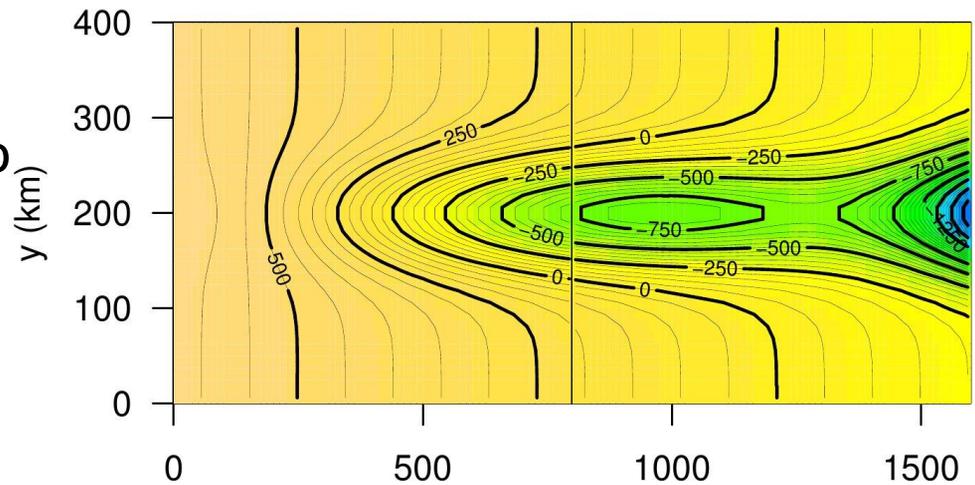
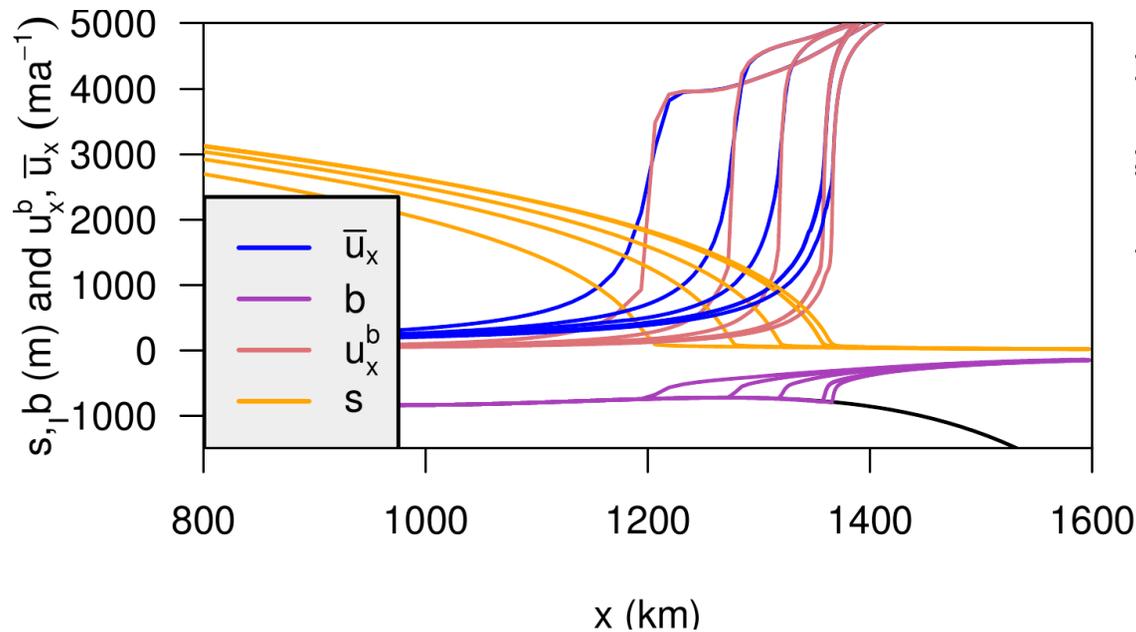
# “L1L2” Model (Schoof and Hindmarsh, 2010).

- ❑ Uses asymptotic structure of full Stokes system to construct a higher-order approximation
  - Expansion in  $\varepsilon$  -- ratio of length scales  $\frac{[h]}{[x]}$
  - Computing velocity to  $O(\varepsilon^2)$  only requires  $\tau$  to  $O(\varepsilon)$
- ❑ Computationally much less expensive -- enables fully 2D vertically integrated discretizations. (can reconstruct 3d)
- ❑ Similar formal accuracy to Blatter-Pattyn  $O(\varepsilon^2)$ 
  - Recovers proper fast- and slow-sliding limits:
    - SIA ( $1 \ll \lambda \leq \varepsilon^{-1/n}$ ) -- accurate to  $O(\varepsilon^2 \lambda^{n-2})$
    - SSA ( $\varepsilon \leq \lambda \leq 1$ ) - accurate to  $O(\varepsilon^2)$



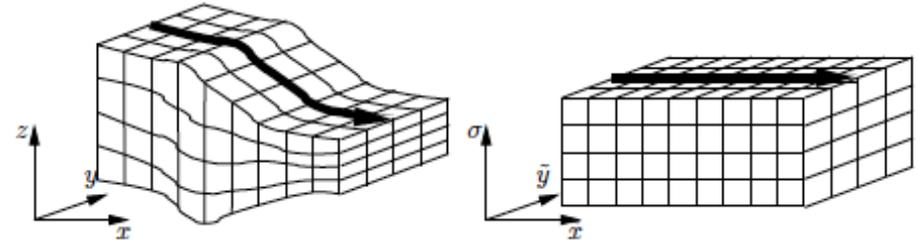
# BISICLES results - Grounding line study

- ❑ Bedrock topography based on Katz and Worster (2010)
- ❑ Evolve initially uniform-thickness ice to steady state
- ❑ Repeatedly add refinement and evolve to steady state
- ❑ G.L. advances with finer resolution
- ❑ Appear to need better than 1 km



# Discretizations

- ❑ Baseline model is the one used in Glimmer-CISM:
  - Logically-rectangular grid, obtained from a time-dependent uniform mapping.
  - 2D equation for ice thickness, coupled with 2D steady elliptic equation for the horizontal velocity components. The vertical velocity is obtained from the assumption of incompressibility.
  - Advection-diffusion equation for temperature.



$$\frac{\partial H}{\partial t} = b - \nabla \cdot H\bar{\mathbf{u}}$$

$$\frac{\partial T}{\partial t} = \frac{k}{\rho c} \nabla^2 T - \mathbf{u} \cdot \nabla T + \frac{\Phi}{\rho c} - w \frac{\partial T}{\partial z}$$

- ❑ Use of Finite-volume discretizations (vs. Finite-difference discretizations) simplifies implementation of local refinement.
- ❑ Software implementation based on constructing and extending existing solvers using the Chombo libraries.

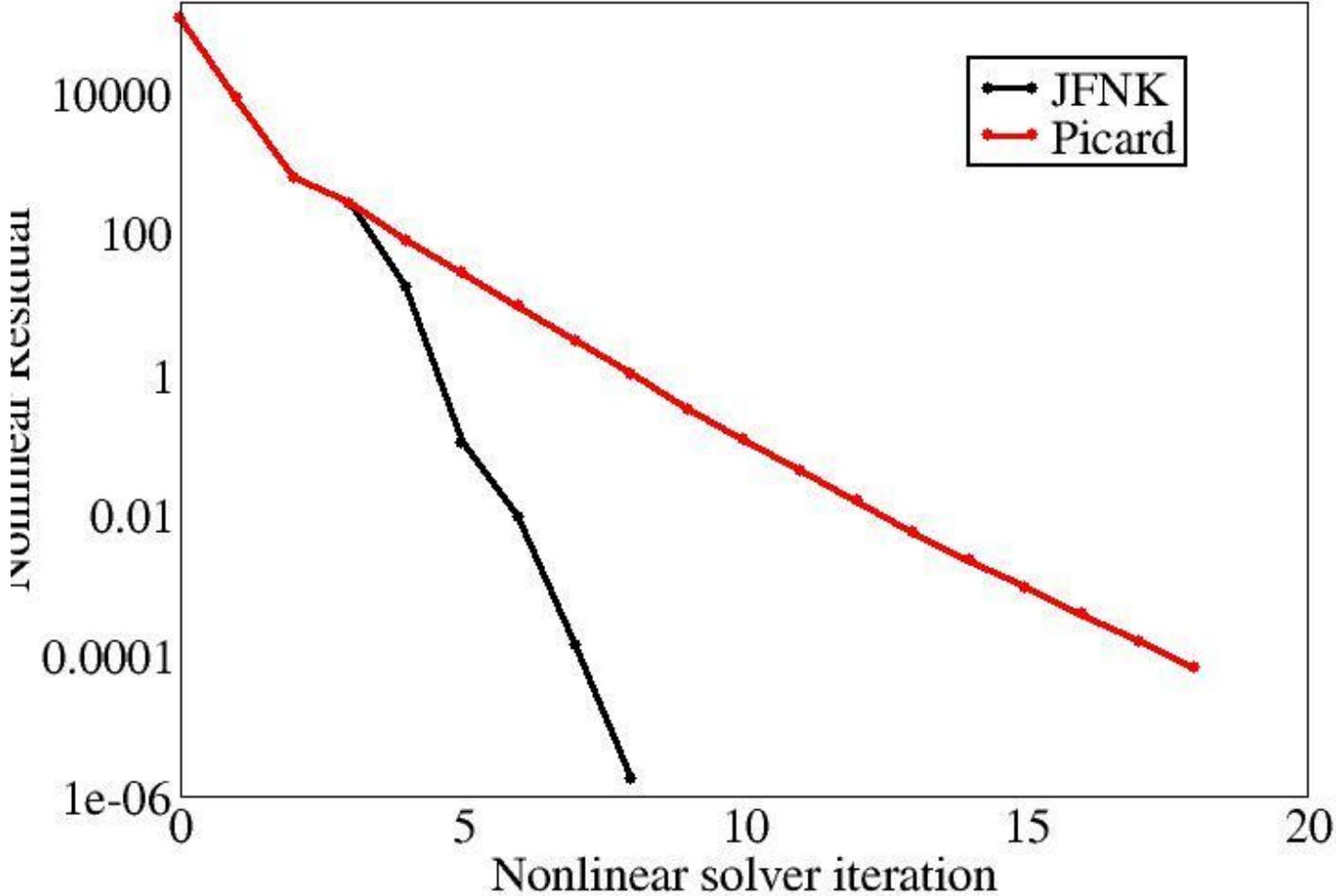
# Nonlinear Solvers

- ❑ Most computational effort spent in nonlinear ice velocity solve.
- ❑ Picard iteration:
  - Robust
  - Simple to implement
  - Slow (but steady) convergence
- ❑ Jacobian-free Newton-Krylov (JFNK):
  - More complex to implement
  - Works best with decent initial guess
  - Rapid convergence
  - Well-suited for Chombo AMR elliptic solvers
- ❑ Approach - use Picard iteration initially, then switch to JFNK when convergence slows



# Nonlinear Solvers (cont)

Nonlinear Solver Convergence

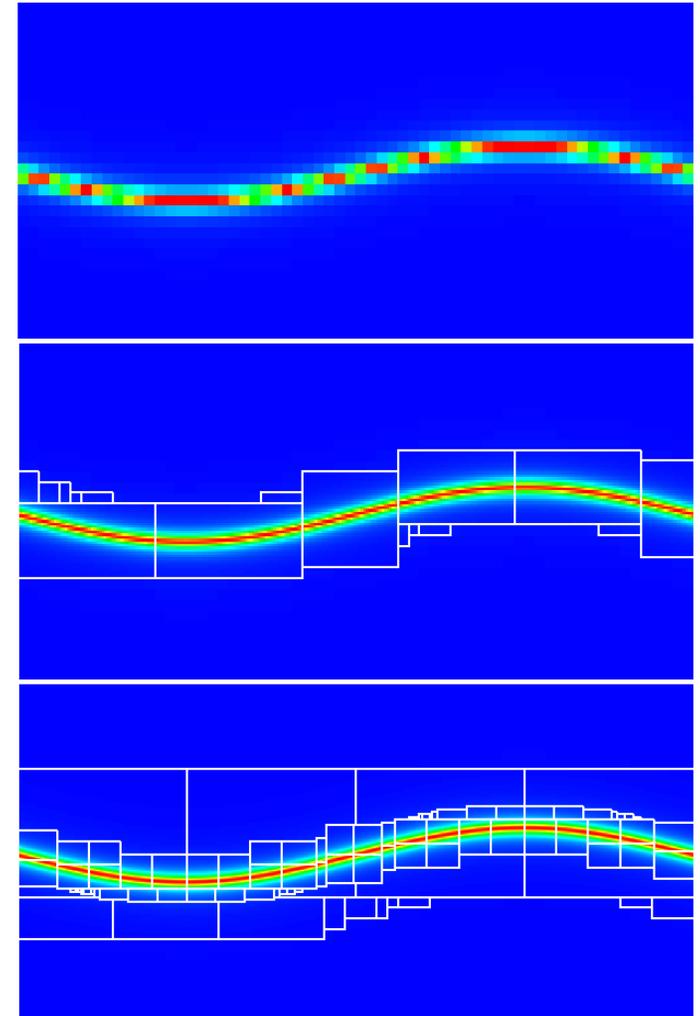
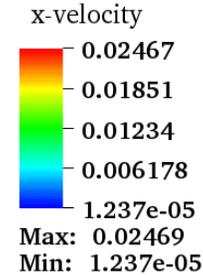


# BISICLES Results

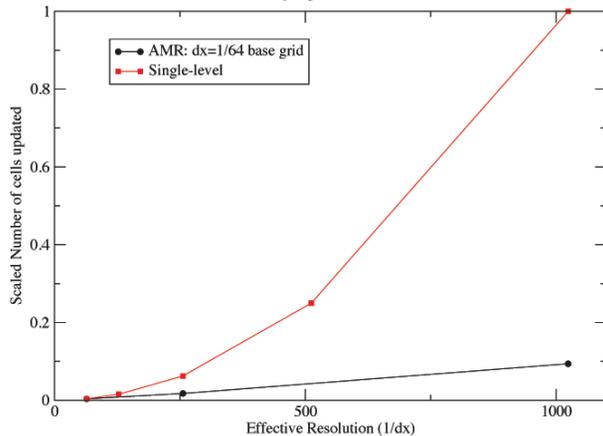
## ❑ Ice-stream Simulation

[based on Pattyn et al (2008)]:

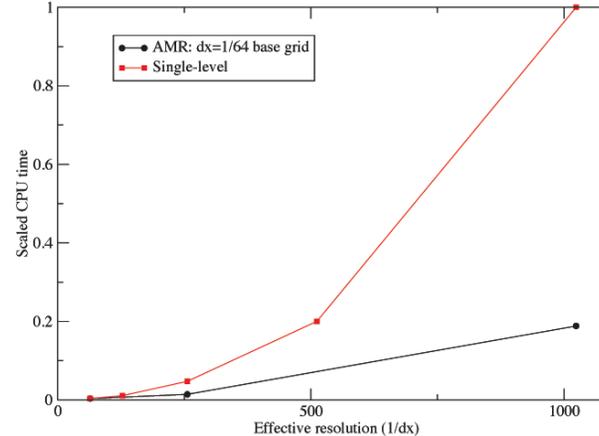
- High resolution is required to accurately resolve the ice stream.
- AMR simulation allows high resolution around the ice stream at a fraction of the cost of a uniformly refined mesh.



Number of cells updated  
Scaled by highest-resolution run

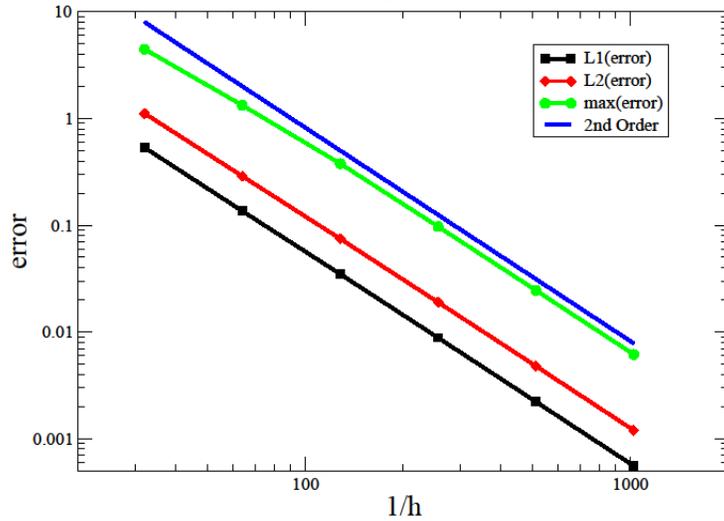


CPU Times for AMR vs. non-AMR  
Scaled by highest-resolution run

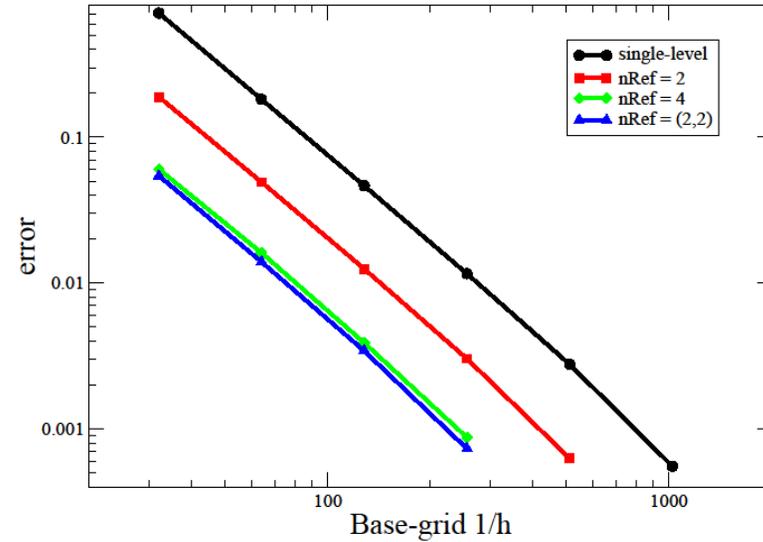


# Numerical Accuracy and Convergence

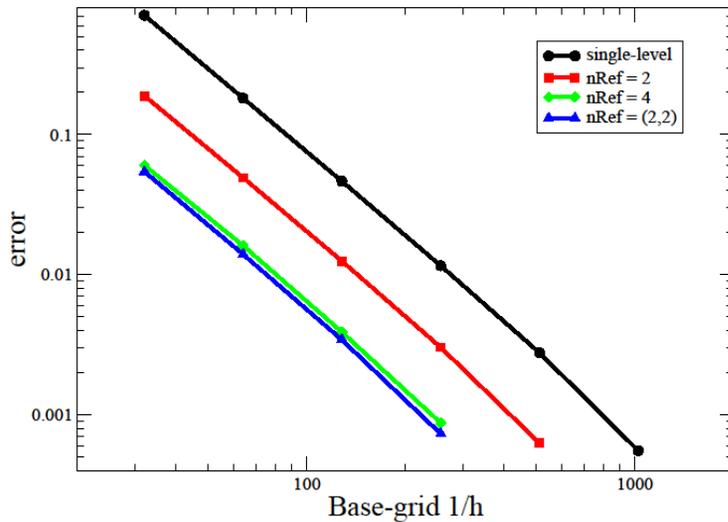
Richardson Convergence of x-velocity  
(single-level)



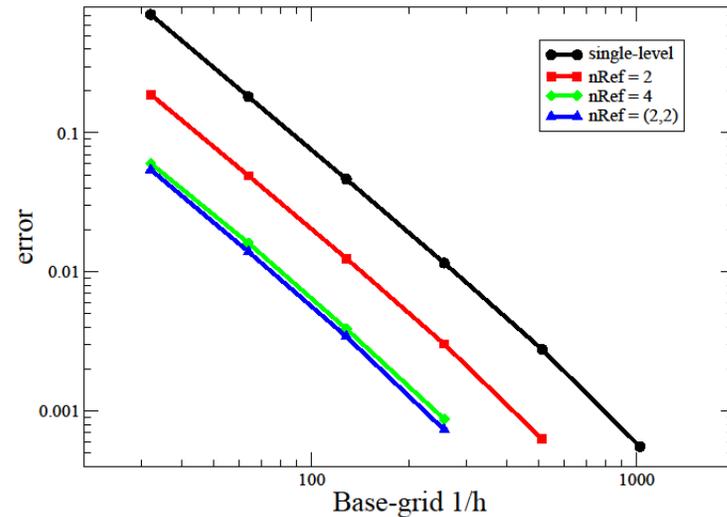
x-velocity AMR Convergence  
L1-norm



x-velocity AMR Convergence  
L1-norm



x-velocity AMR Convergence  
L1-norm



# Continental-scale: Antarctica

- Ice2sea geometry
- Temperature field from Pattyn and Gladstone

